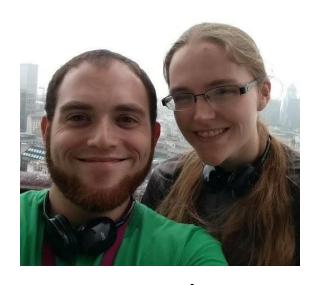


**Graphics Architecture** 

Windows Subsystem for Linux



## About us



Jesse Natalie
Developer on Direct3D



Steve Pronovost
Lead Windows Graphics Kernel

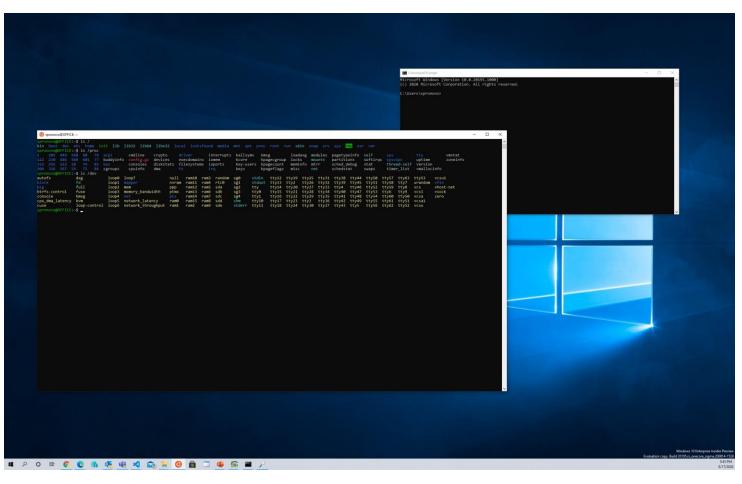
## What is WSL?

- Windows Subsystem for Linux
  - Infrastructure to run Linux applications inside of Windows
  - Today only terminal applications are supported

# Why WSL?

- But can't you just run Linux inside of a VM already?
  - Yes, but managing a VM is a pain and not user friendly
- WSL is all about developers
  - Creating a friendly and integrated experience for developers that needs both a Windows and Linux development environment
    - Some tools run best or only on Windows
    - Some tools run best or only on Linux
  - Get the best of both worlds
    - Developer can run their Windows and Linux development workflow from a single PC
      - No clunky dual boot setup
      - No need for multiple PCs
      - No need for manually managed VM

## WSL



- Terminal integration
- Filesystem integration
- Windows / Linux interop
- ... and many more
- Limited to terminal applications today

## WSL 1 vs WSL 2

### • WSL 1

- Linux userspace running against an emulated Linux Kernel
- Linux userspace isolated in a pico process
- Linux userspace call to kernel trap and emulated on top of ntos

### • WSL 2

- Full Linux userspace and Linux kernel running in a VM
- Same integrated experience
- Better compat (no more kernel emulation)

# Most requested WSL features

- Access to the GPU from within WSL
  - Mostly for compute
  - Most requested is access to NVIDIA CUDA API
  - Subject of this talk
- Ability to run GUI applications
  - Going beyond a terminal only experience and the ability to run X11 and Wayland applications
  - This is the subject of our other XDC talk
    - X11 and Wayland applications in WSL

# Bringing GPU to WSL

- We want to share the GPU(s) with the host
  - Not dedicated assignment
  - All host GPU available to WSL VM
  - Both host and WSL VM can submit work simultaneously to the GPU
- We want to flexibly manage the resources
  - No partition of video memory or fix scheduling quantum
  - Resource assignment based on applications need
- We want to enable a broad set of APIs
  - CUDA, OpenCL, OpenGL, and more
    - DirectX 12 is an implementation details that allow us to get there.

# WDDM GPU Para-Virtualization (GPU-PV)

- WDDM Windows Display Driver Model
  - Thin abstractions for the GPU that all graphics and compute APIs are based on
  - Abstract and manage GPU access for multiple clients
  - Think about it as DRM & KMS
- Para-Virtualization
  - Level of abstraction is the WDDM interface
  - Project the compute/rendering portion of the WDDM interface in a VM so driver can interact with it as if the GPU was local
- Was designed precisely for these usage scenarios
  - Windows Defender Application Guard for Edge
  - Windows Sandbox
  - Device Emulator (e.g. Hololens emulator)
- Extending to support Linux Guest, including WSL

## WDDM Architecture

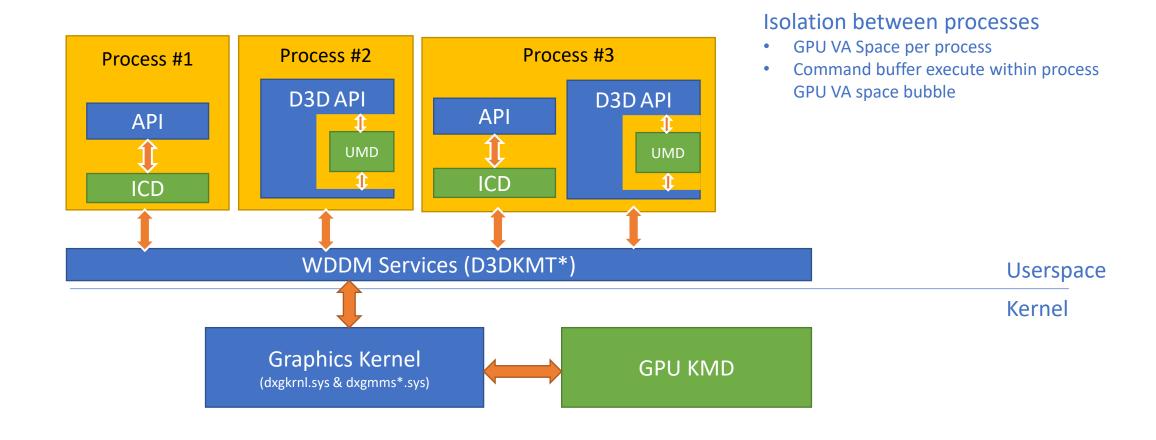
#### Allocate GPU memory Request GPU VA mapping D3D API Request CPU pointer to GPU memory **API** Create synchronization object Submit work **UMD** (User Mode Driver) **ICD** (Installable Client Driver) WDDM Services (D3DKMT\*) Userspace Kernel **Graphics Kernel GPU KMD** (dxgkrnl.sys & dxgmms\*.sys) (Kernel Mode Driver)

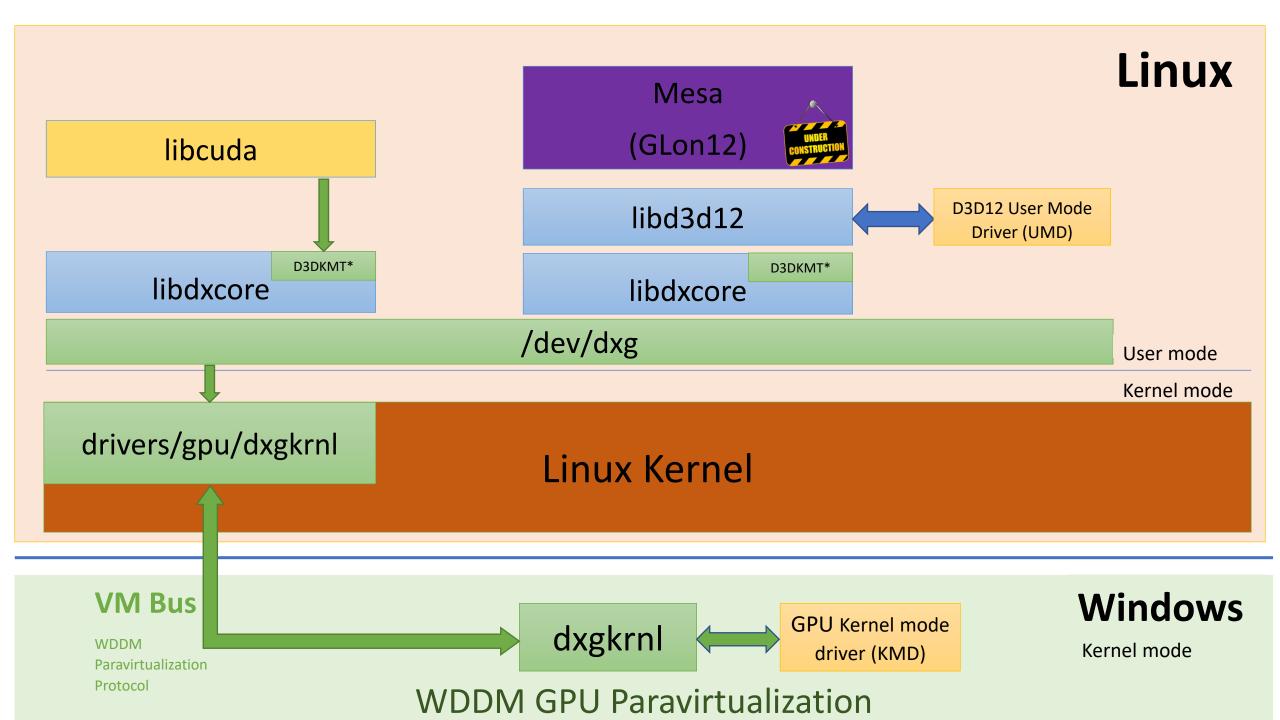
WDDM Services low level and API agnostic

Enumerate GPU Create Device

Create Context / HwQueues

## WDDM Architecture

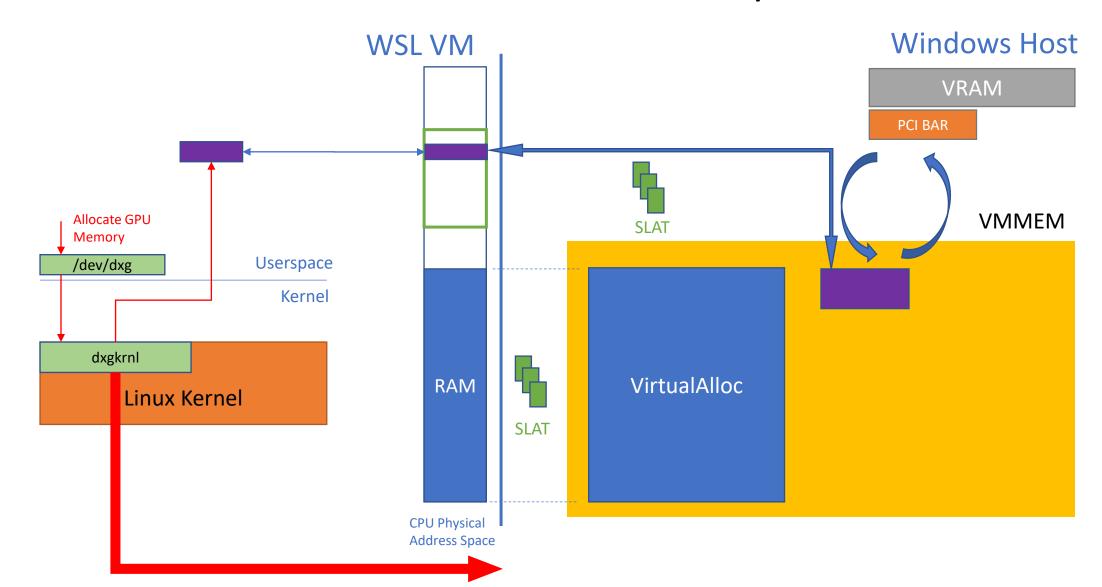




# Dxgkrnl Linux Edition

- Open source
  - <a href="https://github.com/microsoft/WSL2-Linux-Kernel/tree/linux-msft-wsl-4.19.y/drivers/gpu/dxgkrnl">https://github.com/microsoft/WSL2-Linux-Kernel/tree/linux-msft-wsl-4.19.y/drivers/gpu/dxgkrnl</a>
- Not a straight pass-through
  - Some WDDM API implemented locally
  - Some a combination of local and messages to the host
  - Fundamentally memory manager, scheduler and GPU are on the host
- No data copy
  - Only control information exchanged over VM bus
  - Data in command buffers or GPU surfaces shared between guest and host

# Guest CPU Access to GPU Memory



## **WDDM 3.0**

- Seamless support in WDDM3.0+
  - User mode driver compiled for Linux included in driver package
  - Host driver store mounted in Linux
  - Works out of the box
- Integrated into the Windows Driver Certification process
  - IHV Partner adding WSL 2 configured system to their test pool
  - HLK contains WSL 2 specific test validating driver

# WSL Graphics Userspace

## Goals

- Support breadth of existing Linux compute APIs
  - CUDA
  - OpenCL
  - Eventually graphics APIs like OpenGL/Vulkan too
- Minimize redundant/unnecessary work from driver vendors
- Support hardware-accelerated ML like TensorFlow

NOT trying to introduce new competing APIs

# How to get compute acceleration in WSL

- Two possible approaches
  - Ask driver vendors to port ICDs for APIs apps are using
  - Ask driver vendors to port UMD, we port D3D, we build layers to support APIs in terms of D3D
- ICD approach means continued asks on driver vendors for new APIs
  - E.g. 3+ APIs across 4+ vendors
- Mapping layer approach improves both Windows + WSL
  - 1 UMD per vendor, 1 mapping layer per API
  - Enables us to leverage DirectML as backend for ML frameworks
  - Mapping layers can be used to decrease vendor burden for supporting Windows
- Also possible for ICDs to be ported
  - CUDA in WSL works this way

# What exists today

### DXCore

- APIs for enumerating GPUs and querying properties
- Similar role to DRM render nodes

### • D3D12

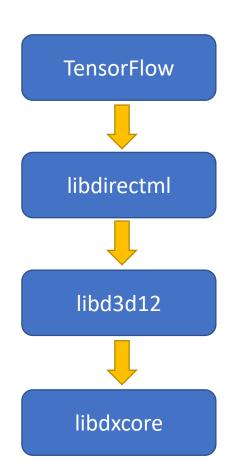
- Requires D3D12 UMD to be ported as well
- UMDs available or in development from all Windows GPU vendors

### DirectML

 Layer on top of D3D12 to provide highly optimized GPU-accelerated ML operators

### TensorFlow

Uses DirectML backend in WSL



# What exists today - notes

- Compute-only functionality
  - Rasterization pipeline is available, but no swapchains / window integration
- Intention of D3D in WSL is implementation detail for GPU access
  - Not trying to introduce a new API for apps no SDK planned
  - Added only to allow GPU access for higher level frameworks / APIs
- D3D stack is same code that runs on Windows
  - All components involved modified to dual-compile
  - Fixed lots of non-conformant code depending on MSVC quirks
  - Replaced Windows-specific constructs with cross-platform code
  - Wrote header shim with #defines/typedefs for things that come from Windows SDK
  - Clang caught several real bugs with its better warnings

# What exists today — TensorFlow

- TensorFlow on DirectML
  - Runs on a wide variety of hardware
    - CUDA is NVIDIA
    - ROCm is a limited set of newer AMD hardware
  - Consistency/conformance
    - We test and work with all hardware vendors for consistent compute results
  - Easy to set up (just pip install tensorflow-directml)
- https://github.com/microsoft/tensorflow-directml
  - Working closely with the TensorFlow community to bring this feature upstream so that it's available in the official build of TensorFlow going forward

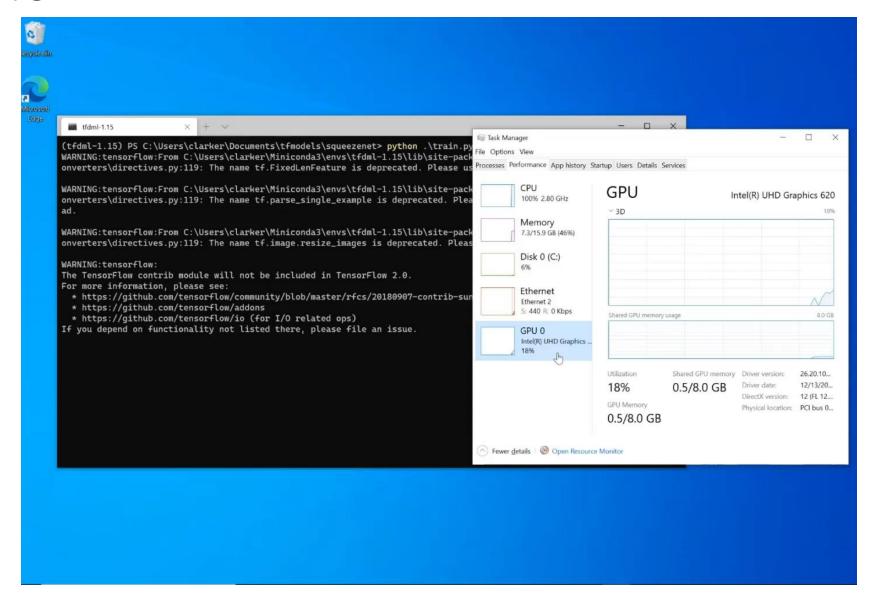
# Shipping as binaries

- Attempting to be distro-agnostic
  - Both Microsoft code (D3D, DML) and WSL drivers
- Note quite statically-linked, but close
  - Only external dependencies on libc
  - C++ runtime and other dependencies included
  - No exceptions crossing module boundaries
  - Technically linking against musl in our build, but in a glibc-compatible way

## What's in the works

- OpenCLOn12
- OpenGLOn12
  - Both leveraging Mesa
  - Both currently working on Windows WSL efforts not yet started
  - OpenGL requires solving window integration: hard problem
    - Lots of open design questions, not intrinsically hard due to Mesa/GL
    - Some work here underway see later talk for non-accelerated WSL window integration: "X11 and Wayland Applications in WSL"

## Demo



# More info / how to try it out

• <a href="https://aka.ms/gpuinwsldocs">https://aka.ms/gpuinwsldocs</a>